

Use of Recon-3D in Scene and Vehicle Documentation presented by **Daniel W. Vomhof III 4N6XPRT** Systems www.4N6XPRT.com 8387 University Avenue - La Mesa, CA 91942 - USA Ph: (619) 464-3478 - Email: dv3@4n6xprt.com for **SCARS 2023 Conference** South Carolina Accident Reconstruction Specialists July 23-28, 2023 Mt Pleasant, SC

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Use of Recon-3D in Scene and Vehicle Documentation Daniel W. Vomhof III

- ACTAR # 484
- EIT

- Involved in AI/AR work since 1976



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METHOD DRIVING SCHOOL 461-9090

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OF TECHA

1982

Recon-3D & Cloud Compare

* This is not the typical Recon-3D and Cloud Compare presenation. For typical Recon-3D presenatations (which ARE important) see the Cloud_compare_comparisons-Patrick_Davis.pdf and the WYMAN_Symposium_Lidar_App.pdf presentations that are included as separate downloads

 This presentation is geared specifically towards the vehicle accident investigation and reconstruction field.

Recon-3D & Cloud Compare

 This presentation deals with considerations as to app operation selection and accuracy within the Recon-3D tool.

*The Cloud Compare portion takes the user through the steps to obtain crush measurements with Cloud Compare.

What is it? What is it not? Why use it?

 Recon-3D is an Apple App to be used on either an Apple iPhone or Apple iPad that has the LIDAR function

*It combines the LIDAR measurement function with photogrammetry using the video taken while "scanning" the object/area of concern

Recon 3D What is it? What is it not? Why use it?

*It is not meant as a replacement for a "real" scanner (i.e. - FARO, Leica, etc) *It does not have the density of scan points the larger scanners have *It also doesnt require the tripod or multiple scans of the larger scanners ***It doesnt** have the associated costs of the larger scanners.

What is it? What is it not? Why use it?

*****Cost - relatively low

*Flexibility - You walk around and scan, you cover the area of intrest, you don't have to set up a tripod multiple times, you don't need to pick up and set down the scanner multiple times, you just walk around and scan.

What is it? What is it not? Why use it?

- *Time In many instances you can cover the area of intrest in 2 minutes or less.
- *"Accuracy" the accuracy is at least as good as a rolling wheel, and often times better.
- Documentation it allows for documentation of area data for later possible use with minimal cost

Screens



Source caronna Accident Reconstruction Specialists - 2023



Plans **Restore Purchases**

1 Month Plan

Cloud Processing: 10 scan daily upload limit | 30 scan monthly upload limit **On-Device Processing: Unlimited** Maximum 10 min scan time for resolutions of 5mm or greater Share scans

\$ 74.99

🕺 1 Year Plan

Share scans \$ 499.99

5 Additional Scans

limit



 (\mathbf{X})

Plans

100

Restore Purchases

★When you click the "+" button, you are presented with the SCAN SETTINGS. These are, per the most recent training, is the settings to be used by the CLOUD processing.

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Screens



Screens ***Units** - I use INCHES, also available are METERS, FEET, and CENTIMETERS *Mode - In general you will want to use STANDARD which is the melding of the photogrammetry with the LIDAR *****SCAN DENSITY - Due to recent changes, you will

probably want 5 mm



Screens

*Scan Density - "tighter" densities (1,2,3,or 4 mm) can be set, but you will not be allowed to scan for the "full" 10 minutes

 Depth of Reconstruction -This is how far into the distance will be included.
 In general 5-10 meters (~15-30 feet) will be sufficient.



Screens

*****Target Detection - If you are using the APRIL targets to help set scale in your scan, you want this ON, however, for a variety of reasons, OFF has become my preferred mode. I have not seen a negative hit in my scans by not using the targets.



*****Target Distance - For a variety of reasons, I set my targets at 72 inches. If you have the ability to utilize a larger distance for scenes and vehicles, it would be advisable to do so, as it is always better to interpolate rather than extrapolate.



*SAVE SCAN SETTINGS You have to save the settings in order to proceed.

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The previous Settings were set from the main menu. By setting the settings here, it saves time in the field, as the "base" settings are pulled up for each scan. The settings can be changed on a case by case basis if desired.



⋆To start a scan, click the "+" button, which then brings up the NEW **PROJECT NAME** screen. It is advisable to name your scans instead of going the "date-time" route

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 This is the name I am using for a scan of my 2004 Hyundai Santa Fe for this presentation.

*Settings used for the scan are 5mm, 5m, No Targets.



*This sample scan took 1 minute 10 seconds to complete, that is 3 circuits around the vehicle. The 08:50 showing is the time remaining for the possible 10 minute scan time.

 Click the white circle with the square to stop the scan



*When you stop the scan you are presented with this screen. Given that I have completed a (in theory) "successful scan" I **ALWAYS ALWAYS ALWAYS** select SAVE FOR **LATER.** The other selection I may make is RESTART. This is done when I have problems mid scan.



What's Next? What would you like to do? PROCESS ON DEVICE PROCESS ON CLOUD SAVE FOR LATER RESTART CANCEL

*****Once the scan is saved, you can click on it and then either process on your device, or process on the cloud, or both.



Standard Mode

Created On: 2023-06-26 12:22:10 PM





(i)

sample for presentation

- ★ If you decide to process on the cloud, it uploads and processes using the settings input prior to your scan.
- If you choose to process on the device you are again presented with the settings in case you want to change any settings for the "on device" processing.
- The processing starts out showing you the video recorded as part of the scan. The next several pages are frame grabs of the video.





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Screens

*Processing on the device goes through 7 "passes".

*To process this scan on my iPhone 12 Pro took 33 minutes.

*Some screen grabs of the processed point cloud follow -





	Recon 3 "Accuracy"	D
Expert AutoStats® Model Data Page 1 Data Page 2 Data Page 3 2004 HYUNDAI SANTA FE (Print File Output DXF Output /6) 4 DOOR 4X2 UTILITY	103.221354 122009 AXY 103.122009 017761 AXZ 103.221352 527557 AZY 4.527592
Horizontal Dimensions Length 177 Wheelbase 103 Front Bumper to Front Axle 34 Errort Rumper to Front of Hood 6	Vertical Dimensions Height 73 in. Ground to:	z 80
Note - No tai wheelbase in wheelbase as AutoStats is	rgets. Howe the scan is s we have it 103 inches.	ver, 103.1 inches, in Expert

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Recon 3D "Accuracy"

*Whats important to us as Vehicle Accident Investigators??

*Are the measurements reasonably correct?

*Do the measurements obtained from the scans reflect the "real life" measurements?

*Will the measurements obtained result in "correct" calculated values?

*To that end

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Recon 3D "Accuracy" * Ped Test at SATAI in 2023 * Instrumented impact speed 34-37 mph





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Recon 3D "Accuracy"

★5.88-6 = -0.12★(-0.12/6)*100=-2.0%



"Accuracy"
*64.83-65 = -0.17
*(-0.17 / 65)*100 = -0.26%



"Accuracy"
*70.789-71 = -0.211 ft
*(-0.211/71)*100 = -0.29%



"Accuracy" ***In multiple instances I have** "measured" a 72 inch distance in Recon-3D. I generally find that I get a distance within +/-.75 inches. $\star (0.75/72) \times 100 = +/- 1.0\%$ *From the SATAI test it can be seen that the accuracy is, for that test, -2%

or better.

*Think, rolling wheel, tape, pacing -how often have you been MORE THAN 2% off? Have you ever checked to see?

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Cloud Compare Trim, Clean, Scale *Now that you have a Point Cloud, What next??



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*One piece of software that will allow you to view and edit the point cloud.

*Once you have the E57 file, processed on either your device or the cloud, it needs to be cleaned up and scaled to the preferred units (if using Cloud Compare). The units when first imported into Cloud Compare is METERS.

- *1 Meter = 3.28084 feet
- *1 Meter = 39.37008 inches

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 Most "Good" CAD software packages have the capability to handle Point Clouds. Cloud Compare is being used here because it is, well, "FREE", and is also a well featured piece of software.
 Cloud Compare can be downloaded

from -

https://www.danielgm.net/cc/release/

*The first video will illustrate what needs to be done.

 Please note, when trimming, to place points, left click on your mouse, to "close" a "loop", right click on your mouse.

★ Play Video 1 in "Cloud Compare videos" folder - All videos are without sound, you just have to watch the mouse movements.

*The second video shows the same vehicle after the crash test, trim, rotate, and scale the point cloud.

★ Play Video 2 in "Cloud Compare videos" folder



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*Now that both vehicles are trimmed, they need to be aligned so that a crush "slice" can be generated.

★ Play Video 3 in "Cloud Compare videos" folder





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 Once aligned, a slice can be taken from which crush measurements can be obtained.

★ Play Video 4 in "Cloud Compare videos" folder



 Once a slice has been obtained, and the vehicle is aligned along with the X-Y Axis, crush measurements can be obtained

★ Play Video 5 in "Cloud Compare videos" folder



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 Final Crush Measurements for all 6 vehicles involved in the three SCARS Crash Tests conducted in July 2022 follow

*As stated on the slides *The X dimension = the Crush Depth
*The Y dimension = the incremental Crush
Lengths
*The UNITS = inches

***V1 Crush Measurements**



***V2 Crush Measurements**



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***V3 Crush Measurements**



Cloud Compare Crush Measurements ***V4 Crush Measurements**



***V5 Crush Measurements**



***V6 Crush Measurements**



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Daniel William Vomhof III, E.I.T.

Certified Accident Reconstruction Specialist

EDUCATION:

- B. S. Engineering
- A. S. Engineering
- A. S. Surveying

ACCIDENT SPECIFIC EDUCATION

PROFESSIONAL CERTIFICATION:

- Engineering E.I.T. Registration #XE088556, 1993
- Accredited Traffic Accident Reconstructionist, The Accreditation Commission for Traffic Accident Reconstruction, Registration #484, 1993
- Certified Accident Reconstruction Specialist Institute of Police Traffic Management, 1983

EXPERIENCE:

Expert Witness Services, Inc.

(1992-present)	_	Accident	Reconstructionist.
(1984-1992)	_	Accident	Reconstruction Assoc.
(1981-1984)	_	Accident	Reconstructionist.
(1976-1981)	_	Technicia	an.

Primary responsibilities include:

- Evaluation of traffic signal timing related to vehicle, pedestrian, and motorcycle accidents
- Reconstruction of vehicle, pedestrian, and motorcycle accidents
- Evaluation of Pedestrian/Facility/Walking Surface interactions
- Measurement and evaluation of lighting as it affects perception of hazards
- Measurement and evaluation of sound levels
- Documentation of vehicle evidence and scene conditions through photography and measurements
- Preparation of scale scene diagrams and other exhibits for use in depositions, arbitration hearings, and trial.

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(1992-present) - General Manager/Technical Support/Programmer

Primary responsibilities include:

- Maintain data and Software Programs available for sale
- Provide Technical Support to program owners
- Provide data to Accident Investigators throughout North America when requested via email, phone, or fax

October 1994 June 1992 August 1986

(3,196+ Hrs)

City of La Mesa - Traffic Engineering (1988-1992) - Engineering Technician I.

Primary responsibilities in the field included preparation, review, and inspection of traffic control plans; preparation of striping, signing, and traffic signal plans and layouts for the field crews; traffic signal system coordination; field changes to traffic signal timing plans; and determination of proper sign type and placement to remedy existing traffic problems.

Primary responsibilities in the office included monthly review of accident reports for possible conditions contributing to the accidents which would be correctable by engineering projects; preparation of individual and system traffic signal timing plans; preparation of staff reports and exhibits for public hearings; and presentation of staff reports at public hearings.

Acted as Primary Interface between Traffic Engineering and Police Department in issues of Traffic Signal timing and downloads

SWORN TESTIMONY:

- Qualified in San Diego and San Bernardino Superior Court on: * Traffic Signal timing sequence and "who had the green" issues
- Qualified in San Diego, El Cajon, Vista, San Bernardino, Pasadena, Solano, and Wisconsin Superior Courts on one or more of these issues: *Time-Speed-Distance-Force calculations *Speed survey design, conduction, & data analysis *Preparation of scale diagrams of roadways *Lighting considerations *Vehicle and pedestrian paths of travel *"Normal" vehicle speeds for an area *Human factors - Perception, Reaction, Line-of-Sight *Vehicle and Occupant movements *Speed from Damage

Computer Software Programs Developed and Maintained:

- D.W. Vomhof III, D. W. Vomhof, and S. Young, 4N6XPRT StifCalcs, 4N6XPRT SYSTEMS, La Mesa, CA (2007-2021)
- D.W. Vomhof III and D. W. Vomhof, Expert AutoStats, 4N6XPRT SYSTEMS, La Mesa, CA (1993-2022)
- D.W. Vomhof, D. W. Vomhof III, and S. Young, Expert VIN DeCoder, 4N6XPRT SYSTEMS, La Mesa, CA (2007-2021)
- D.W. Vomhof III, D. W. Vomhof, and B. Cunningham, 4N6XPRT StifCalcs, 4N6XPRT SYSTEMS, La Mesa, CA (2003-2006)
- D.W. Vomhof and D. W. Vomhof III, 4N6XPRT Ped & Bike Calcs, 4N6XPRT SYSTEMS, La Mesa, CA (1996)

Publications:

A-B-G Stiffness Values ... How to Research and Calculate Step-by-Step, Published by IPTM Press, Copyright 2014