



# iPhone and iPad LiDAR Scanner for Evidence Documentation

Presented by Robert Wyman

Wyman Enterprises, Inc. 786-246-8100



## SYMPOSIUM ON TRAFFIC SAFETY



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## UPDATED THEME FOR THIS PRESENTATION

Due to the rapidly-growing interest and acceptance of the iPhone/iPad LiDAR scanner over the last year, in the Traffic Crash Reconstruction industry, this presentation will now emphasize real-world LiDAR utilization instead of providing a more basic introduction to the technology.

As such, this presentation may encompass a shorter presentation time than allocated in the schedule.



## UPDATED THEME FOR THIS PRESENTATION

Interestingly, the Crime Scene Investigation industry is still evaluating this technology, and still worried about the (non-existent) circumstance of having cellphones “inspected” by Criminal Defense Attorneys.

We can discuss why this issue is unfounded ... for CSI’s as well as Crash Reconstructionists ... if you are interested, just let me know.



## This audience, regarding iPhone/iPad LiDAR:

(time to raise your hands, since everyone LOVES to participate 🙋🙋)

- How many currently use LiDAR?
- How many do not use, but are familiar with the LiDAR features?
- How many think LiDAR is a simple cellphone novelty and not a useful tool?
- How many work for an agency not allowing cellphone use?



This audience, regarding iPhone/iPad LiDAR:

**Brief Scanning Demo  
(if everything works!)**



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Introduction

# LiDAR

## Light Detection and Ranging

Similar in scope to...

Radar ... Radio Detection and Ranging  
Sonar ... Sound Navigation and Ranging





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**Introduction**

# LiDAR

Also called "laser imaging, detection, and ranging" or simply "3-D Laser Scanning"

Wikipedia

"It is a method for determining ranges by targeting an object or a surface with a laser and measuring the time for the reflected light to return to the receiver"

Developed in 1961-1963, soon after development of the laser.



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**Introduction**

# LiDAR

LiDAR is now commonly used in...

- Surveying
- Archaeology
- Geology
- Forestry
- Airborne mapping - topography
- Airborne mapping – littoral
- Artificial Intelligence / Machine Vision
- Automated/Autonomous Vehicles

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LiDAR Hardware

LiDAR consists of an “emitter” element that projects an infrared laser pattern onto a target surface.

The surface must be within a physical range consistent with the output power of the emitter.

A receiver element detects the reflected light and processes it to calculate and obtain the desired output.



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**LiDAR Hardware**

## Emitter range...

- Higher power = longer range = greater cost
- Lower power = shorter range = lesser cost
  
- At present, the well-known brands of large laser scanners are still required for wide-area and/or distant targets.

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**LiDAR Hardware**



*Note: Graphics obtained from various webpages reporting on this topic.*

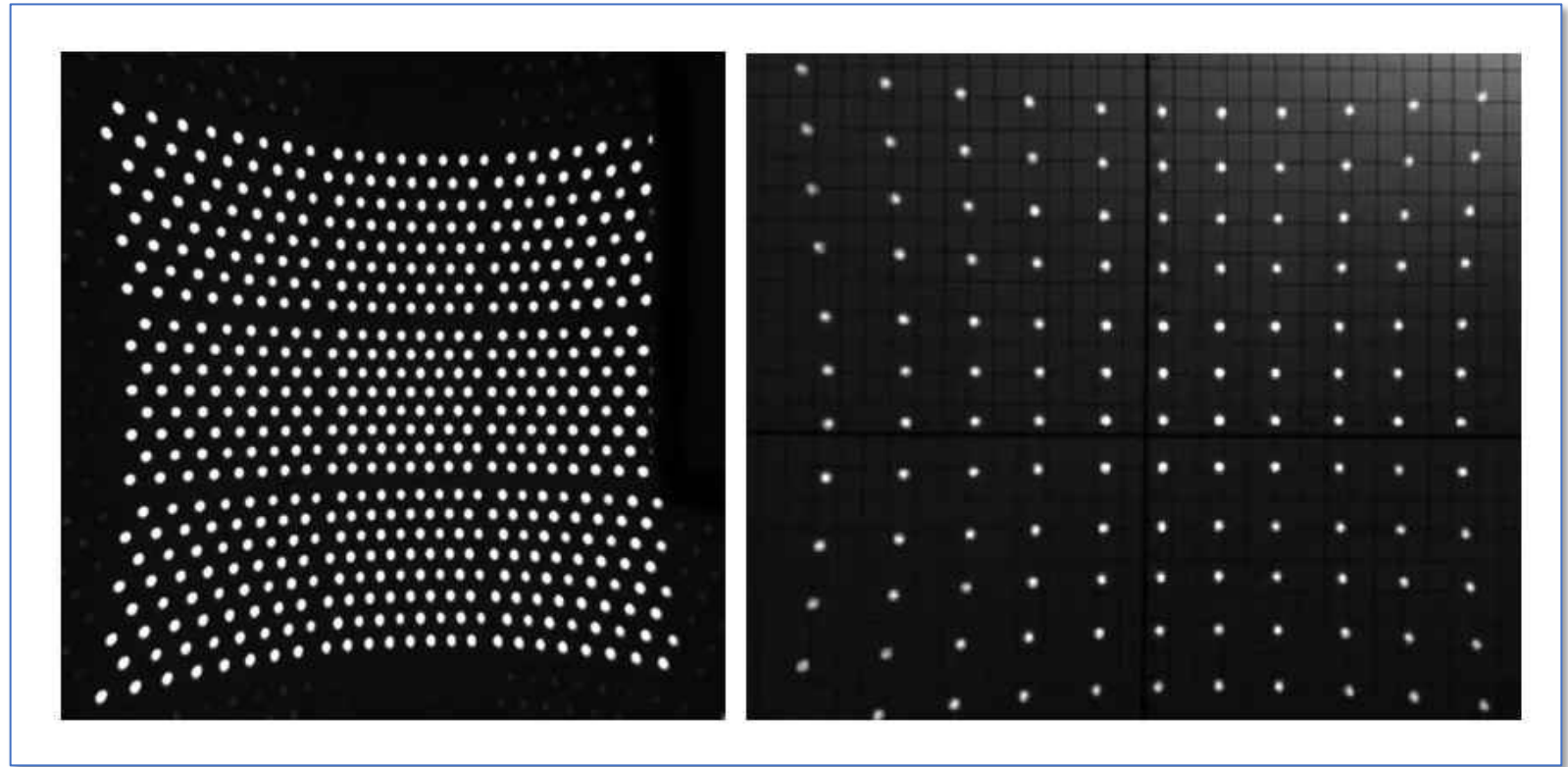
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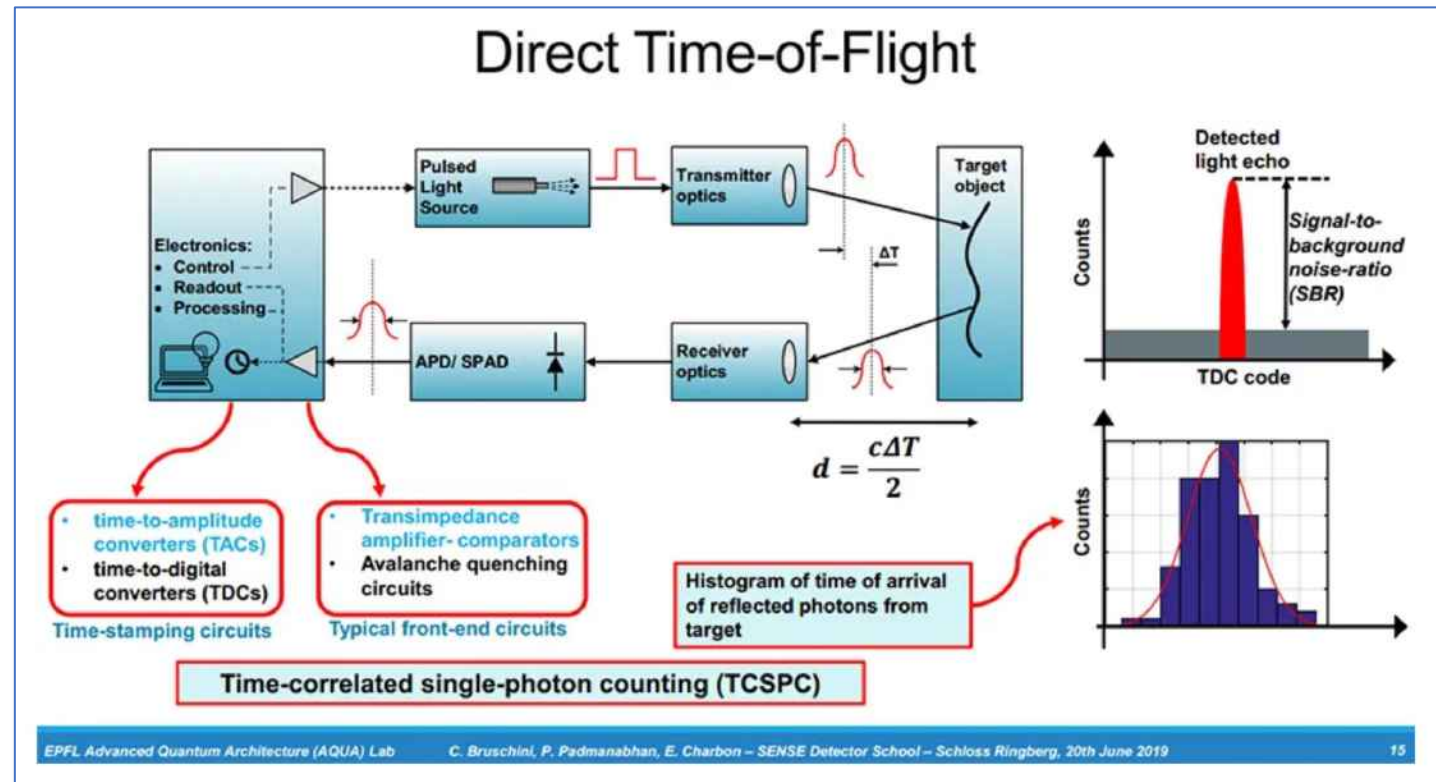


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## Introduction LiDAR Hardware



*Note: Graphics obtained from various webpages reporting on this topic.*



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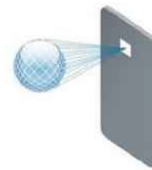
Introduction  
LiDAR Hardware

## Typical 3D Sensing Systems

Modules for 3D Sensing Platforms



### Structured Light



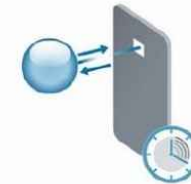
- Pattern projector (dots or masks): pre-defined, randomized pattern
- NIR camera for pattern imaging
- Depth calculation by triangulation

### Stereo Vision



- 2 NIR cameras, RGB camera (optional)
- Depth calculation by triangulation
- Dot-pattern projection for texture and disparity computation enhancement

### Time-of-Flight



- Distance estimation by stop-watch (dToF) or phase shift (iToF):
  - 1D Direct ToF (dToF): SPAD pixel
  - 2D/3D Indirect ToF (iToF): Demodulation pixel
- IR illumination: Fast-pulsed and/or modulated light

*Note: Graphics obtained from various webpages reporting on this topic.*



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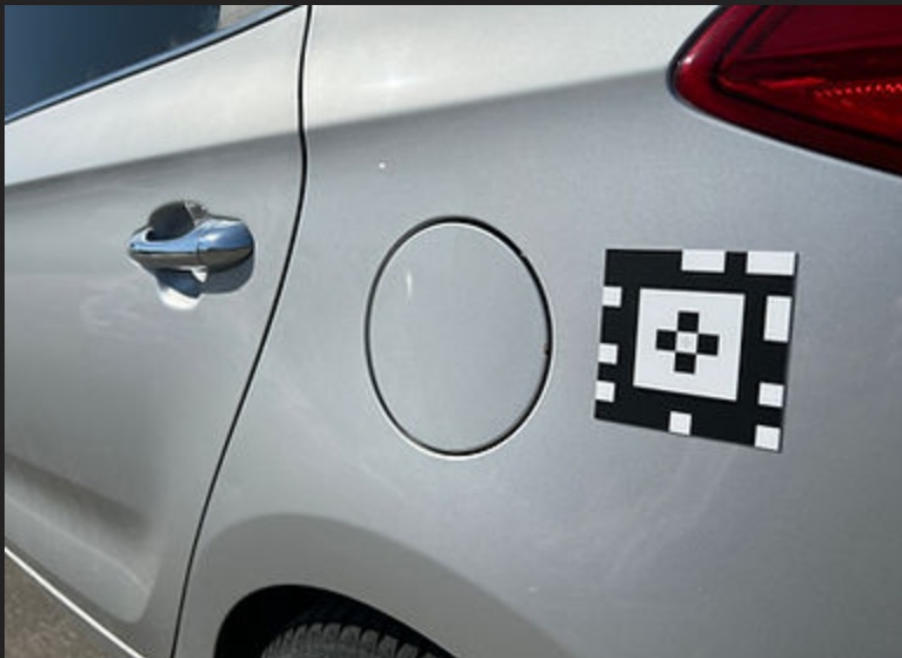
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Introduction

**LiDAR Hardware**

## April Tags (Targets)

### R3D TARGET KIT



The Recon-3D target kit provides the user with a set of different sized AprilTags to use in their scanning workflow. A set of magnetic targets can be placed on vehicle bodies or metal door frames while the vinyl sticker targets are useful to affix to metal, plastic or wood surfaces.

Target Kit includes:

2 x 8" Magnets

2 x 6" Magnets

2 x 4" Magnets

2 x 6" Vinyl Stickers

2 x 3.5" Vinyl Stickers

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Introduction

LiDAR Hardware

**LiDAR Background**

The iPhone and iPad LiDAR first appeared on iPhone/iPad “Pro” versions (Pro and Pro Max), beginning with the iPhone 12 in 2020.

App development followed, with mostly novelty Apps appearing in the App Store by 2021, and more useful Apps appearing in 2022.



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Initial Apps, and many current Apps, are architectural in nature... geared toward interior home and room measurements.

The first “forensic” App was **Recon-3D** by Eugene Liscio, P.E., released in 2022, after an extensive beta-test period.

Scanning technology continues to evolve, with photogrammetry, GPS, and other features being integrated with lasers.



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Recon-3D continues to evolve as well, and is currently enjoying widespread testing, evaluation and real-world academic and casework use in the Recon field.

For example, Daniel Vomhof, a crash test team member at this conference, has already scanned an estimated 400 hundred vehicles with Recon-3D at crash-testing conferences around the country over the last year.



Introduction

LiDAR Hardware

**LiDAR Background**

Discussions about 3-D scanners in cellphones began over a decade ago.

Apple, Samsung, Microsoft, Google and others received many “new feature wanted” recommendations for a scanner ... but NOT for practical consumer or professional use.

Instead, recommendations were for integration with GAMES, so kids could scan their own environments and create personalized gaming architecture.



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If anyone in today's audience was an attendee at my "iPhone Apps for Crash Reconstruction" conference presentations for IPTM many years ago ...

... you heard me predict that future crash and crime scene investigations will have a phone or similar device capable of high-resolution scene photos, videos, and 3-D scene documentation/measurements.

Back then, this was dismissed as a toy or novelty feature, not a viable professional tool.



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Regarding having a scanner as an input source for kid's games, the increase in school shootings and other juvenile crimes resulted in a marketing shift by the various phone and software companies.

No one wanted a headline reading something like, "School Shooter Planned Escape Route by Scanning Floorplan with iPhone App."

Thus, the scanner feature emphasis shifted to consumer and possible professional use.



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- Sample Apps**

## Apple App Store Sample Titles

3D LiDAR Scanner

3D Scanner App

CamToPlan – 3D Scanner & LiDAR

Canvas: LiDAR 3D Measurements

Dot3D – LiDAR 3D Scanning

Magicplan

MagiScan – AI 3D Scanner app

Metascan – 3D Scanner

Modelar – 3D LiDAR scanner

Pix4Dcatch: 3D scanner





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## Apple App Store Sample Titles

Polycam 3D Scanner

Qlone 3D Scanner

RealScan – 3D Room Design

Recon-3D

RENDER: Floor plans in seconds

RoomScan Pro LiDAR floor plans

Scandy Pro: 3D Scanner, 3D App

Scaniverse – 3D Scanner

ScanKit

SiteScape – LiDAR 3D Scanner



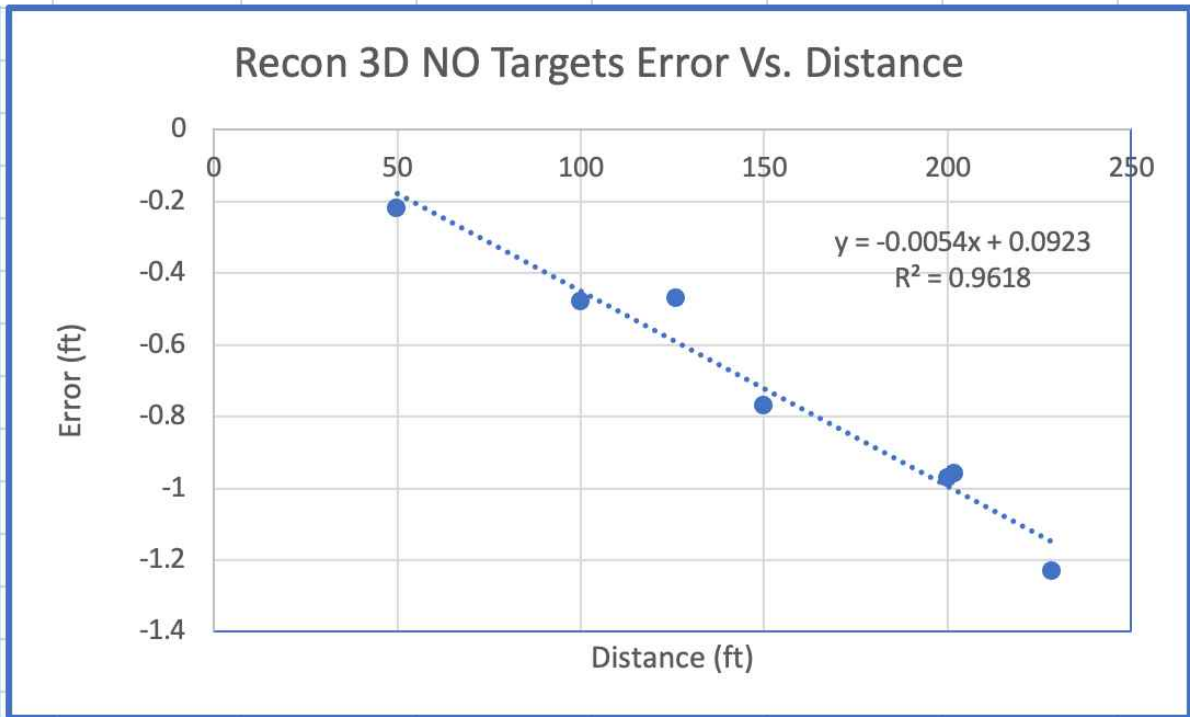
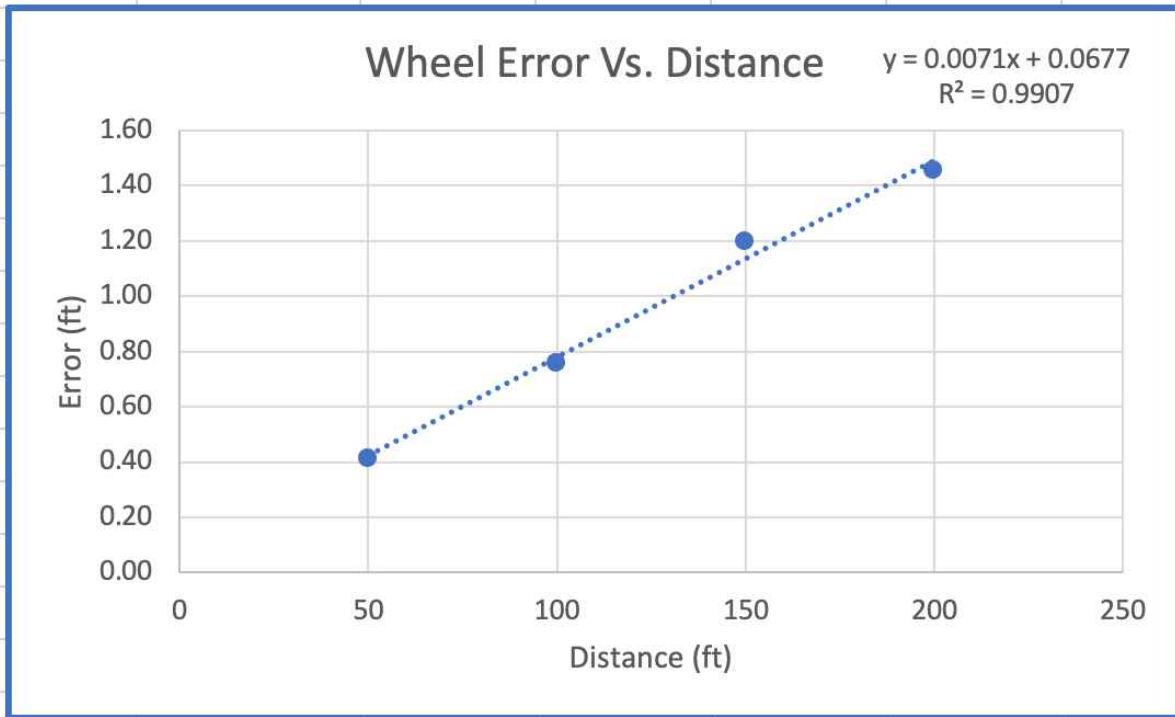
# Andrew S. Rich, BSME, ACTAR, ASE

## Rich Consulting, LLC

	Total Station	Wheel	RC Ortho	RTK	Recon3D w/ Targets	Recond 3D NO Targets		Wheel	RC Ortho	RTK	Recon3D NO Targets	Recon 3D with Targets
50	49.96	50.375	49.927	49.91	50.22	49.74		0.41	-0.03	-0.05	-0.22	0.26
100	99.95	100.71	99.966	99.95	100.17	99.47		0.76	0.02	0	-0.48	0.22
150	149.96	151.16	150.04	149.97	150	149.19		1.20	0.08	0.01	-0.77	0.04
200	199.92	201.375	200.012	199.94	199.91	198.95		1.46	0.09	0.02	-0.97	-0.01
GCP1 to GCP2	76.6	N/A	76.565	76.47				N/A	-0.03	-0.13		
GCP1 to GCP3	125.94	N/A	125.951	125.93		125.47		N/A	0.01	-0.01	-0.47	
GCP1 to GCP4	228.57	N/A	228.578	228.54	228.39	227.34		N/A	0.01	-0.03	-1.23	-0.18
T1 to T2	201.779	N/A	201.956	N/A	201.8	200.82		N/A	0.18	N/A	-0.959	0.021
							<b>RMS Error</b>	1.04 ft	0.08 ft	0.05 ft	0.80 ft	0.16 ft



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Forensic Imaging 32 (2023) 200535



ELSEVIER

Contents lists available at [ScienceDirect](https://www.sciencedirect.com)

## Forensic Imaging

journal homepage: [www.sciencedirect.com/journal/forensic-imaging](http://www.sciencedirect.com/journal/forensic-imaging)

### Using the iPhone's LiDAR technology to capture 3D forensic data at crime and crash scenes

Sören Kottner<sup>a,\*</sup>, Michael J. Thali<sup>a</sup>, Dominic Gascho<sup>a</sup><sup>a</sup> Zurich Institute of Forensic Medicine, University of Zurich, Winterthurerstrasse 190/52, 8057 Zurich, Switzerland

#### ARTICLE INFO

##### Keywords:

Recon-3D  
Forensic imaging  
Forensic documentation  
3D scanning  
3D imaging  
3D documentation  
Photogrammetry  
Smartphone  
Tablet  
Time of flight

#### ABSTRACT

**Background:** Three-dimensional (3D) documentation of crime and crash scenes is common practice during forensic and medicolegal investigations. Such documentation at a scene is usually carried out by specially trained personnel using various 3D imaging devices and methods, such as terrestrial laser scanners. Unfortunately, this causes the implementation of 3D documentation at the scenes to be expensive and not readily accessible. In 2020, Apple introduced a light detection and ranging (LiDAR) sensor into their high-end mobile devices. In 2022, Recon-3D, an iOS application (app), was launched. This app turns an iPhone or iPad into a 3D scanner and is specifically targeted at crime and crash scene applications.

**Objectives:** The aim of this study was to test the Recon-3D app based on exemplary scenarios to see whether this technology is generally applicable to document crime or crash scenes.

**Materials and Methods:** An iPhone 13 Pro in combination with the Recon-3D app was used to document two indoor scenarios, a mock-up crime scene and a garage, as well as an outdoor scenario of a parked car. Each scenario was documented multiple times.

**Results:** On average, data acquisition for one scene took less than 2 min. Known distances within the scenes were measured with a mean absolute error of 0.22 cm and a standard deviation of 0.18 cm.

**Conclusion:** The imaging workflow was simple and quick, enabling any person to perform 3D documentation at a crime or crash scene. Overall, Recon-3D appeared to be a useful application for forensic investigators.



## A B S T R A C T

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S. Kottner et al.

Forensic Imaging 32 (2023) 200535



Fig. 4. Screenshots of the 3D point cloud from the garage. Views of the scene from different angles are given in images a – c. The point size of the data points was increased to provide a better visualization of the data.



Fig. 5. Screenshots of the 3D point cloud from the parked car. Views of the car from different angles are given in images a – c. The license plate has been painted over to hide the original license plate number. The point size of the data points was increased to provide a better visualization of the data.





2023-01-0614 Published 11 Apr 2023



# Accuracy and Repeatability of Mobile Phone LiDAR Capture

**Seth Higgins Miller, Alireza Hashemian, Robert Gillihan, and Saylor Benes** J.S. Held LLC

**Citation:** Miller, S.H., Hashemian, A., Gillihan, R., and Benes, S., "Accuracy and Repeatability of Mobile Phone LiDAR Capture," SAE Technical Paper 2023-01-0614, 2023, doi:10.4271/2023-01-0614.

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## Recon-3D Measurement Accuracy Study for Small Scenes

Eugene Liscio &amp; Jihwa Lim

ai2-3D Forensics, Ontario, Canada

### ABSTRACT

Recon-3D is an iOS mobile application dedicated to crash and crime scene documentation of small scenes, which fuses the Light Detection and Ranging (LiDAR) sensor and video frames to reconstruct 3D geometry as point clouds. In a recent training course, sixty students were asked to set up a mock scene with numbered measurement markers, scan the scene with their mobile devices, and provide 10 measurements between the numbered measurement markers in their scenes (n = 600). The results of these measurements were compiled and tabulated for accuracy. The average error of all participants was found to be approximately -2 mm with a standard deviation of 15 mm. The mean absolute error was found to be approximately 1 cm and the maximum error for any one participant was 10 cm. Expressing the errors in terms of percent, the average error for all participants was approximately -0.078% with a maximum percent error of 2.83%. Although these measurement exercises were uncontrolled, they show that the majority of errors (2σ), fell within 3 cm. Future studies using point-to-point measurements should include repeatability tests in a controlled environment as there were several variables which were unaccounted for in this study.

**Keywords:** LiDAR, crime scene investigation, crime scene reconstruction, forensic science

### ARTICLE INFORMATION

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Citation: Liscio E, Lim J. Recon-3D Measurement Accuracy Study for Small Scenes. *J Assoc Crime Scene Reconstr.* 2023;27:1-10.

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eliscio@ai2-3d.com

### Introduction

Crime and crash scene documentation has benefited greatly by the use of total stations, terrestrial LiDAR scanners (TLS), and the use of photogrammetry. These technologies offer ways of documenting scenes in a highly detailed and efficient manner. Past studies have focused on LiDAR technology and photogrammetry in applications such as collision reconstruction, crime scene documentation, bloodstain pattern analysis, and bullet trajectory analysis. There has been great acceptance of the TLS and photogrammetry in the forensic field, especially the use of aerial imagery from drones in crash scene scenarios. These technologies all have

their individual limitations whether it be cost, maintenance, portability, required level of training, or flexibility. Usually, the technology is available to a dedicated group of individuals who have access to the equipment and have been properly certified and trained.

One of the most limiting factors for smaller companies and police agencies is cost. Many investigators and private forensic engineering firms have been searching for low-cost tools which can provide 3D documentation capability within a reasonable margin of error and accuracy. In this regard, photogrammetry is a strong contender since it requires the use of





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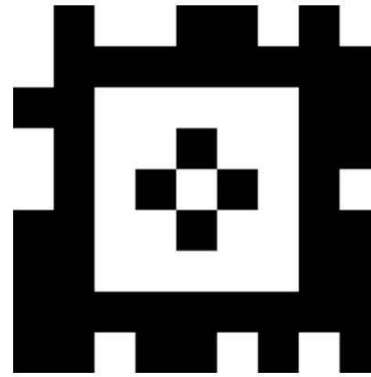


FIGURE 3: AprilTag used in Recon-3D.

AprilTags which have been placed in the scene. As a best practice, the larger the spacing between the AprilTags, the improved error reduction. Once the data is finished processing, the distance between AprilTags is automatically adjusted for scale based on the user's input reference distance. In cases where a reference distance is not available, the scaling of the object is approximated by the distance measurements recorded with the LiDAR sensor, where the accuracy and repeatability are not defined.

### Method

In June 2022, a Recon-3D training class was held through an online platform and students

were given instruction on how the LiDAR sensor works, the use of the app, settings, scanning in varying situations, and how to take measurements using CloudCompare software. Students were also required to complete an assignment as part of the class certification with instructions as follows:

1. Choose an indoor or outdoor area to scan using Recon-3D.
2. Place 10 numbered measurement markers (provided in a PDF and printed on paper) throughout the scene in random positions to include horizontal and vertical measurements. Markers were to be secured using tape or placed on a surface where they would not move during the measurement exercise. Example layout of targets shown in Figure 4.
3. Place two AprilTags in the scene as far apart as possible.
4. Manually measure the distance between the two AprilTags and 10 of the measurement markers with a tape measure (or other instrument).
5. Using Recon-3D, create a new scan and use at least a 5 mm resolution.
6. Enter the reference distance between the two AprilTags.
7. Process the data on the cloud.
8. Once data is processed, download the data, and import into CloudCompare.
9. In CloudCompare, record measurements between the previously manually measured



FIGURE 4: Recon-3D data in CloudCompare software showing an example scene with measurement markers and AprilTags.

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**Error (mm) Distribution, n=600**

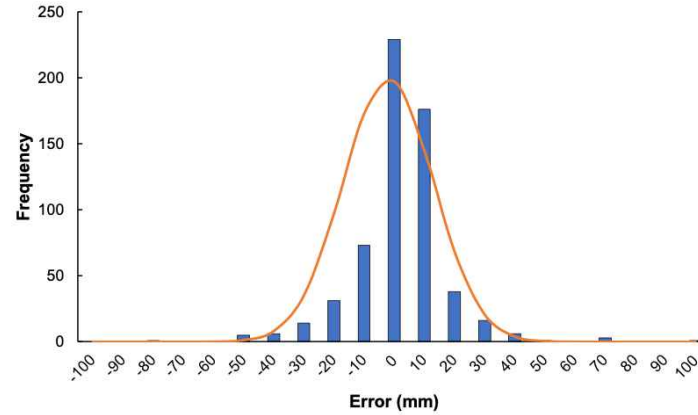


FIGURE 5: Histogram with a normal curve showing distribution of errors from student assignments, n = 600.

**Percentage Error (%) Distribution, n=600**

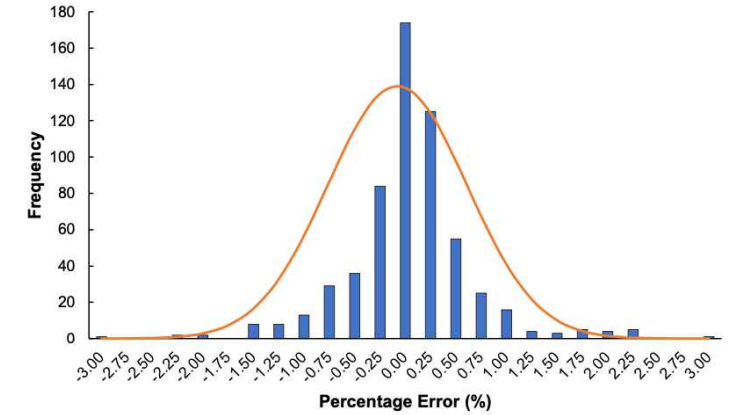


FIGURE 7: Histogram with a normal curve showing the percentage of error distribution, n = 600.

**Absolute Error (mm) Distribution, n=600**

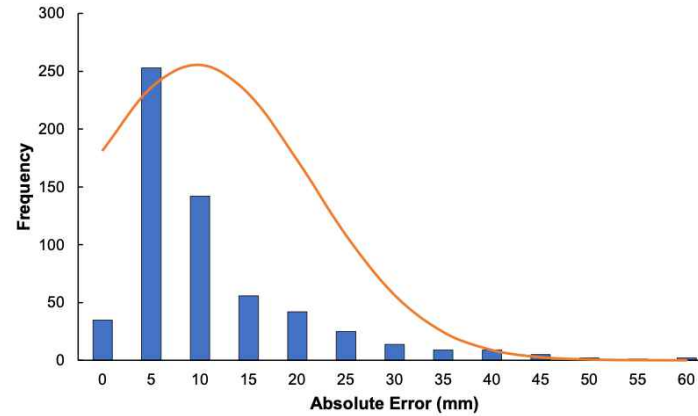


FIGURE 5: Histogram with a normal curve showing absolute errors which is a measure of the magnitude of errors n = 600.

**Absolute Percentage Error (%) Distribution, n=600**

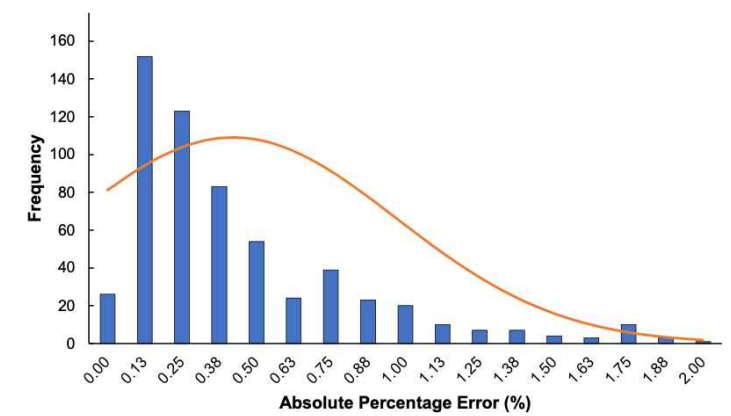


FIGURE 8: Histogram with a normal curve showing the absolute percentage error distribution, n = 600.



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## Other New Products of Interest

# Moasure One

The screenshot shows the Moasure ONE website. At the top left is the 'moasure' logo. The navigation menu includes 'Home', 'Moasure ONE', 'Industries', 'Our Story', and 'Contact Us'. The main content area features a smartphone displaying the Moasure app interface, which shows a measured area with various dimensions and a total perimeter of 244.6ft (3317.5ft²). Next to the phone is the physical Moasure One device, a small black rectangular sensor. To the right of the phone is a yellow starburst graphic with the text 'WE'RE DIFFERENT. SEE HOW'. Below this is the product name 'Moasure® ONE™' with a 5-star rating and '680 reviews'. The price is listed as '\$449.00 USD' with a link to 'Our views on quality'. A dashed box contains a 'One-time price: No additional costs or monthly fees.' section, followed by a paragraph describing the product's capabilities. At the bottom right of this section is a yellow 'Continue Reading' button.



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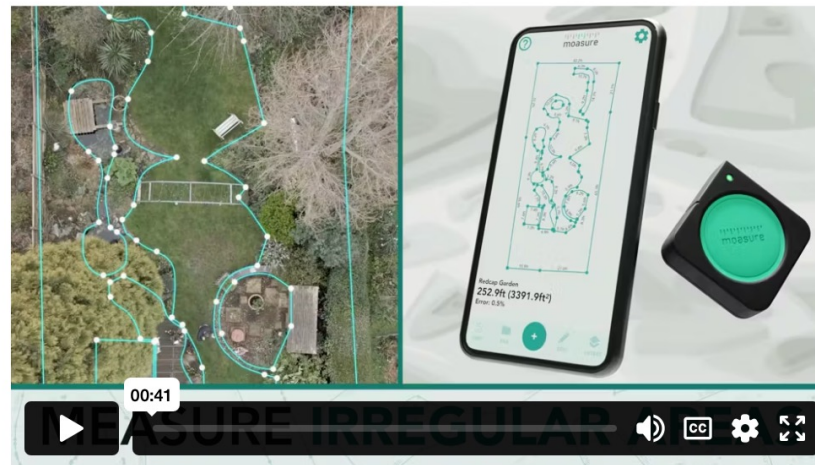
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# Other New Products of Interest

## Moasure One



### Measure & Draw Simultaneously

Effortlessly measure curves and free-form shapes. Simply trace along the edges of an area using Moasure ONE to digitally capture the shape and dimensions. Rapidly measure the perimeter and calculate the area of curved lawns, pools and other shapes and spaces – regular or irregular.

**Is It Fast & Accurate?**



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# Other New Products of Interest

# Moasure One

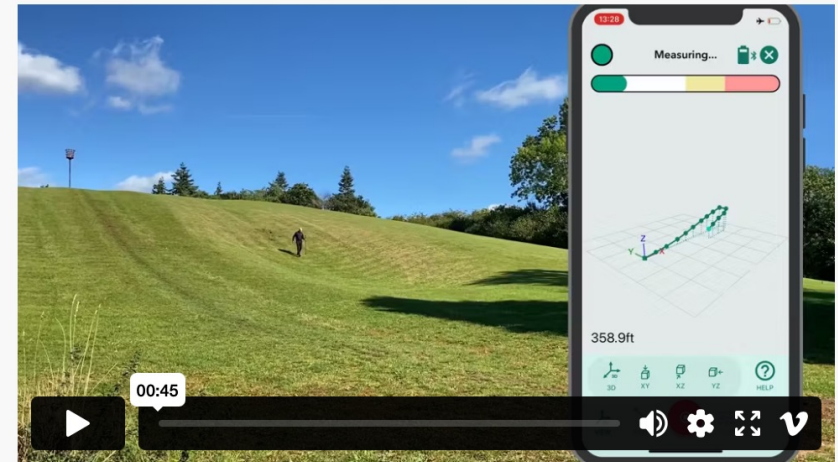
## Capture & Measure Changes in Elevation

As you measure, you'll see Moasure draw a complete 3D site model on your smartphone screen – in real time.

Using powerful motion-measuring technology, Moasure measures its own position in 3 dimensions; capturing changes in elevation as well as calculating area and perimeter – automatically and simultaneously.

View the distance, gradient, or rise and fall – or simply tap any point on the measurement drawing to view the recorded X, Y, & Z coordinate data.

You can now rapidly and accurately map a job site – complete with area, perimeter and elevation in the time it takes to walk around.



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## Other New Products of Interest

# Meazor 3D

### MEAZOR 3D - Future Laser Measure



6-in-1 | 40m Multi-room Scan | Export to CAD | 3D Obstacle Avoidance | 2mm Precision | 3 Apps Integration

[Pre-order Now](#)

Created by  
HOZO Design. Co.

1,174 backers pledged HK\$ 2,853,853 to help bring this project to life.

 Last updated [February 28, 2023](#)

**2023**

# SYMPOSIUM ON TRAFFIC SAFETY

June 26-29, 2023 | Orlando, Florida

- Introduction
- LiDAR Hardware
- LiDAR Background
- Sample Apps
- Measurement Studies
- Phones with Other Devices**

## Other New Products of Interest

# Meazor 3D



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## Other New Products of Interest

# Meazor 3D

HOZO | DESIGN

SALE 

PRODUCTS 

SUPPORT

COMMUNITY 

PARTNER 

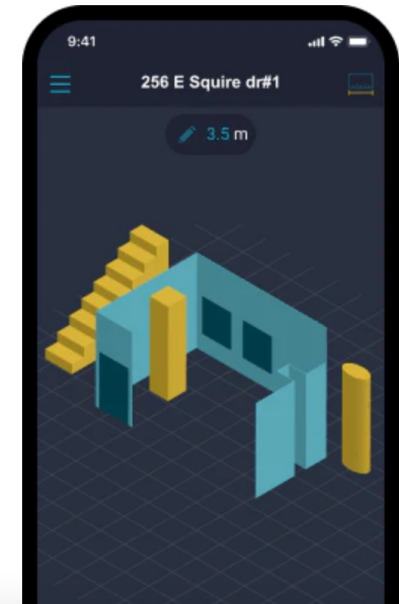


MEAZOR 3D  64 reviews

From \$299.00 \$349.00

ADD TO CART

MEAZOR APP 2.0 available in iOS and Android





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IPTM

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## Other New Products of Interest

# Matterport



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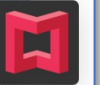
## Other New Products of Interest

# Matterport

### Simplicity through automation.

Cortex AI automates many steps in the model creation process, including blurring faces as needed, choosing the best images from your scans, creating accurate measurements, and identifying different objects.

Once you've finished scanning, Cortex AI allows you to sit back and wait for your completed 3D model to render.



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**Further Research**

## Google Search Keywords for Additional Info, Articles and Tests

iPhone LiDAR

iPhone LiDAR Emitter

iPhone LiDAR Time of Flight

iPhone LiDAR vs. Total Station

iPhone LiDAR vs. Laser Scanner ["brand name"]

iPhone LiDAR vs. Photogrammetry

iPhone LiDAR 3D Scanning

*... and similar sample combinations*



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# Sample YouTube Videos of Interest



“What is LiDAR? (& Why is it on Apple Devices All of a Sudden),” from TheUnlockr



“Georeferencing iPhone 14 Pro LiDAR using Targets,” from Rami Tamimi



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# Sample YouTube Videos of Interest



“iPhone 14 Pro LIDAR vs. Survey Total Station Accuracy,” from Rami Tamimi



“Recon-3D New Version Webinar,” from Eugene Liscio



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# Sample YouTube Videos of Interest



“An interesting discovery using iPhone 12 LiDAR scanner,” from Eugene Liscio



“Laser Scanning vs. iPhone LiDAR,” from Eugene Liscio

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- Further Research
- Conclusions and Recommendations**

# Sample Scans

HOME SUBSCRIBE TRAINING FAQ TUTORIALS ACCESSORIES **SAMPLE DATA** RESEARCH ABOUT CONTACT

## SAMPLE DATA



**Dodge Journey**

Dodge Journey scan with 4m...



**Hummer**

Courtesy of Jason Keller



**Body CSI**

Dummy on tiled floor, 1mm...



**BMW Damaged**

Courtesy of Joseph Catone



**Multiquip Tank**

Multiquip tank scan 5mm...



**Graffiti Belgium**

Courtesy of Jason Keller



**Service House**

Scanned at 5mm resolution



**GMC Plow**

5mm resolution



**Concrete Pillars**

Concrete pillars under bridge



**CAT Equipmen**

CAT Heavy Equipm



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The iPhone and iPad LiDAR features are tools and not toys. They add a new level of portability and always-available scanning functions to your workflow.

Accuracy and Precision are excellent if used with a purposeful scanning methodology.

Reconstructionists should consider testing and perhaps adopting these new technologies, as they can make evidence documentation, measurements and diagrams faster and easier than with other devices.